

IN THE SPECIFICATION:

Please replace paragraph [0016] with the following amended paragraph [0016]:

Spindle heads 36, 38 are moved parallel to axis 26 by a mechanism including a first servo motor 48. First end of first ribbon 16 is rotated by a mechanism including a second servo motor 50 and first end of second ribbon 16 is rotated by a mechanism including a third servo motor 52. Each servo motor is electrically connected to a controller 54. Controller 54 separately controls the operation of servo motors 48, 50, 52 such that each motor 48, 50, 52 is able to operate at a speed different from the operation speed of either of the other two motors. In one embodiment, controller 46 is an Allen-Bradley controller utilizing a touch screen interface such as a ControlLogix/1756 controller available from Rockwell Automation Corporation, Milwaukee Wisconsin, 53202. Due to the independent operation of servo motors 48, 50, 52, the speed, acceleration, and deceleration at which each ribbon 16 is rotated by spindle heads 36 and 38 can be varied with respect to each ribbon as well as to the speed of movement of engagement mechanism 24 along axis 26.